



Septentrio GNSS Solutions



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Contents and Goals of this Presentation

- Septentrio Profile
 - Company profile
 - Product overview
- Technology overview : robust GNSS for harsh environments (interference, multipath, spoofing, vibrations, ionospheric disturbances, etc.) with concrete examples
- PolaRx5 series – GNSS receivers for reference stations and scientific applications
- mosaic series – GNSS modules for large scale hi-accuracy applications
 - Overview
 - Evaluation kits and where to buy ?
 - Eco-systems
- Summary



Company Profile

Septentrio, who we are?

- **Your success is our success**
 - Most accurate and reliable **GNSS position and timing solutions** in the most demanding industrial and scientific environments
- **Our team is your team**
 - Global team of **GNSS HW, SW** and navigation experts developing all core elements of high-quality GNSS receivers.
- **Focus on quality**
 - Partner with you to provide **robust high-quality GNSS positioning products** with excellent integration, application engineering and **service**
- **Global Presence**
 - Located in Leuven, Belgium with regional branches in Los Angeles, CA, Shanghai, Korea and Yokohama (near Tokyo), JPN.
 - Worldwide partner networks

Welcome to Leuven, Belgium:

European innovation capital 2021

Center of excellence for education, innovation and semiconductor technology

KU Leuven

Founded in 1425

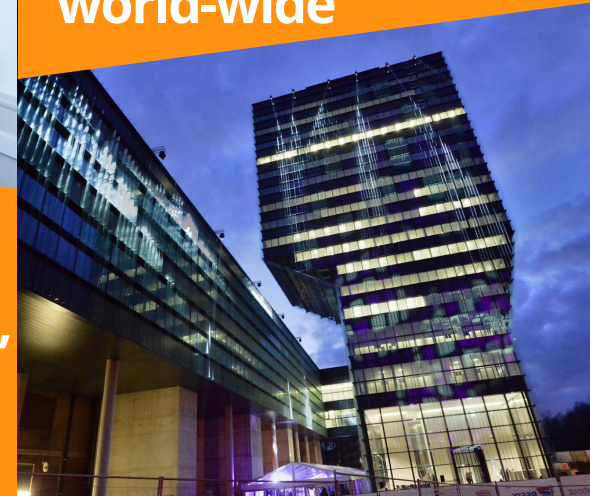
46 000 students

16% international



IMEC

5000 researchers
#1 semiconductor
research institute
world-wide



#1
most innovative
university in Europe,
ranked by Reuters



IMEC : Interuniversity Microelectronics Centre
KU Leuven : Katholieke Universiteit Leuven



Septentrio's Roots



In-depth understanding of designing and building advanced ASIC's and systems



Founder & key shareholder of Septentrio.
Spin off from IMEC, Septentrio was founded in 2000.
Direct access to unmatched ecosystem for digital & analog ASIC design, production & testing.

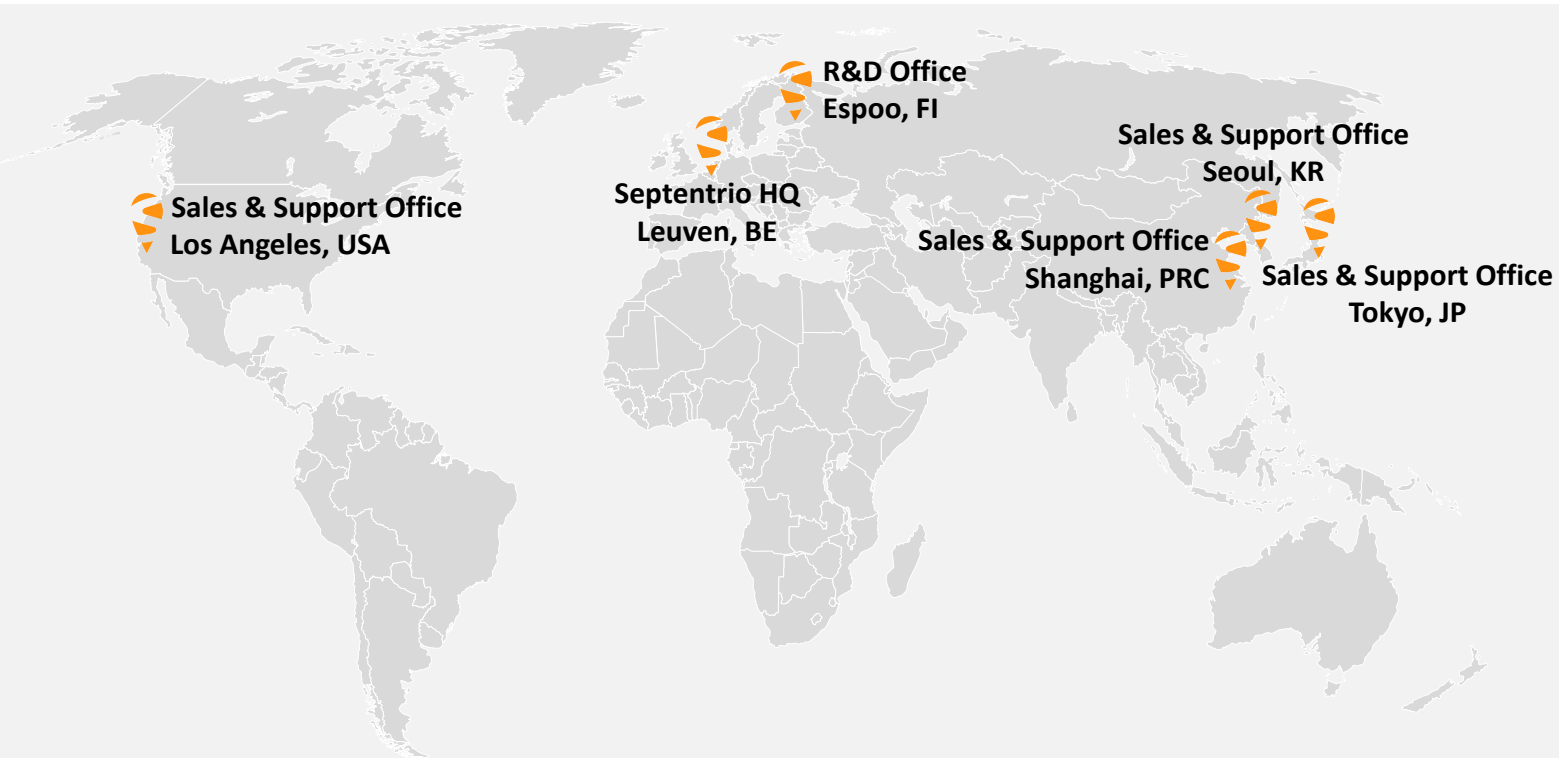


In-depth understanding of GNSS and how to maximize its use



Long term strategic partner since 2002.
All Galileo test receivers designed and built by Septentrio exclusively.
First ever Galileo Receiver made by Septentrio.
Participated in numerous ESA projects in military, avionics & space.
Provided **in-depth understanding of GNSS.**

Corporate Overview



Headquartered in Leuven, Belgium

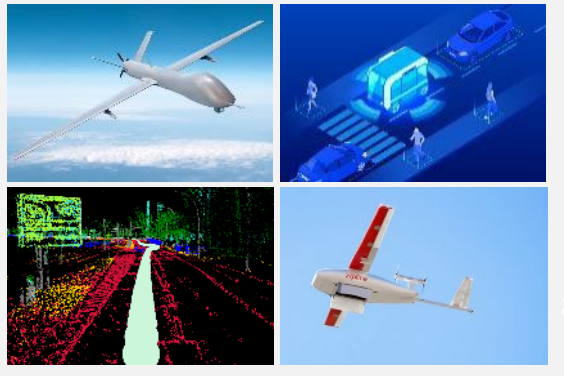
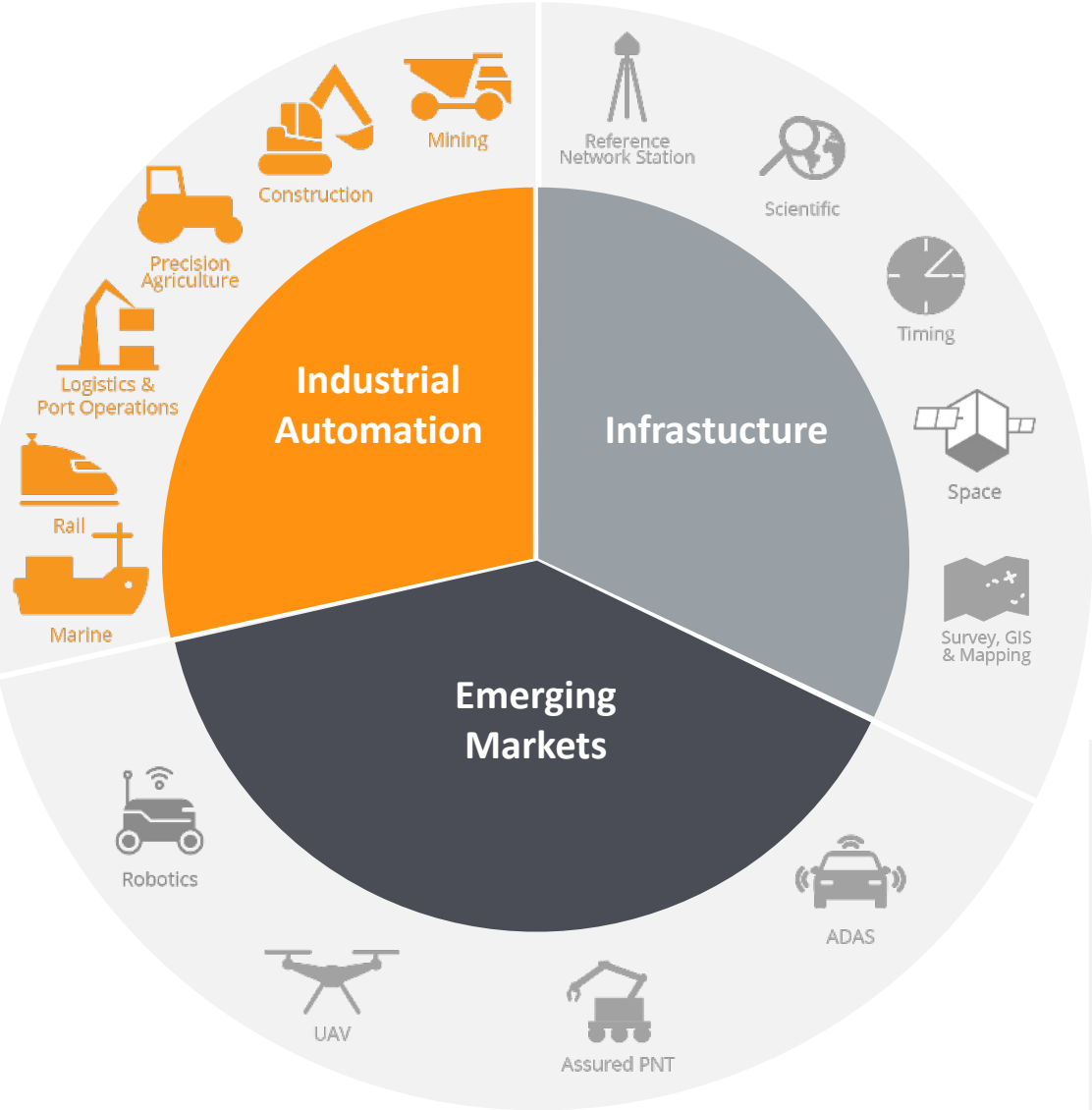
R&D centres in Belgium and Finland.

Global customer base, with sales and support offices close to the large industrial clusters

















130 employees, 60 of which in R&D

ISO 9001 certified

Key application markets



Product overview

| Modules | Boards | Housed Receivers | Antennas | Scientific Receivers |
|---|---|--|--|--|
|  mosaic-X5 <i>Single-antenna</i> |  AsteRx-m3 <i>Single- or dual-antenna</i> |  AsteRx-U3, U3 Marine <i>Dual-antenna, all comms</i> |  AntaRx (Coming soon) <i>Single- or dual- smart antenna GNSS or GNSS-INS</i> |  PolarX5, PolarX5e <i>Reference & scientific</i> |
|  mosaic-H <i>Dual-antenna</i> |  AsteRx-i3 D <i>Non-tethered GNSS-INS</i> |  AsteRx SB3 <i>Single- or dual-antenna</i> |  Various GNSS Antennae |  PolarX5S <i>Ionospheric monitoring</i> |
|  mosaic-T <i>Timing variant</i> |  AsteRx-i3 S <i>Tethered GNSS-INS</i> |  AsteRx SBI3 <i>GNSS-INS</i> | |  PolarX5TR <i>Time and frequency transfer</i> |
|  mosaic-CLAS <i>CLAS variant for Japan</i> |  Interface Board, Development kits | | | |

Technology overview

Robust GNSS for harsh environments (interference, multipath, spoofing, vibrations, ionospheric disturbances, etc.) with concrete examples

Technology overview of Septentrio GNSS receivers

All Satellites

GPS/GLO/GAL/BDS/
QZSS/IRNS

Low Power

~0.5W (Module)
~1W (Board)
~2W (Boxed-type)

High navigation rate,

Low latency

100Hz (INS 200Hz)
Latency : ~10ms

Multi-Bands

L1,L2
L-band, L5, L6

Easy to use

WebUI (NTRIP Server/
Caster integrated, Spectram
Analyzer integrated)
Open Format (SBF)
Free Tool : conversion, analysis

Rich HW Interface

Ethernet
Serial (3 and 4), USB
On-board Logging, PPS

Anti-interference, Anti- Jamming

Automatic notch-filter
Wide-band and chirp
interference

Anti-spoofing

Septentrio's patented
GNSS+ technologies
(Algorism)
OSNMA

Septentrio's patented GNSS+ technologies (Algorithms)

AIM+, IONO+, RAIM+, APME+, LOCK+, INS+

Performance mode

| | | |
|-------------|---------|--------------|
| Stand-alone | SBAS | Differential |
| RTK | RTK-VRS | PPP(L-band) |
| Base | INS | |

Makin (Norway)

Ionosphere Resilience at high latitudes

Interference Mitigation



Multipath of cliffs and excavator boom

Scalable accuracy

Reliable Position and Orientation – even when heavy vibrations

All-in-one, easy to use



Jan De Nul (Belgium)

Ionosphere Resilience



Interference Mitigation
Inmarsat

Scalable accuracy
PPP & RTK

Reliable Heading

Reliable Position and Orientation

AsteRx-U

Kalmar (Norway)



GNSS signal reflections

Difficult environments

- Solution = GNSS/INS
- Powered by multiple GNSS constellations



Avoid accidents

Logistics automation


Naio Technologies (France)



Why Septentrio

- Altus NR3
- Reliability
- Ease of integration
- Support for SSR (L-band + NTRIP)

Renu Robotics (US)



mosaicHAT

- Small and simple to use GPS/GNSS
- Enabling Septentrio's mosaic modules
- Compatible with Raspberry Pi
- USB, UART and FTDI communication
- Open source Hardware

Raspberry Pi

open source hardware

CC BY SA

The image shows a green PCB (Printed Circuit Board) with a white square module in the center. The module has a QR code and the text 'mosaic' and 'SIN2016.0801771'. There are two gold-colored SMA connectors at the bottom. The background is blue.

Why Mosaic

- Multipath near solar panels
- Price
- Integrity info for IMU sensor.

ISRC (Japan)

Why Mosaic

- Multipath near dam
- Fix in limited sky visibility
- PixHawk plug-compatible



At Shikoku Dam

APME+ Advanced Multipath Mitigation



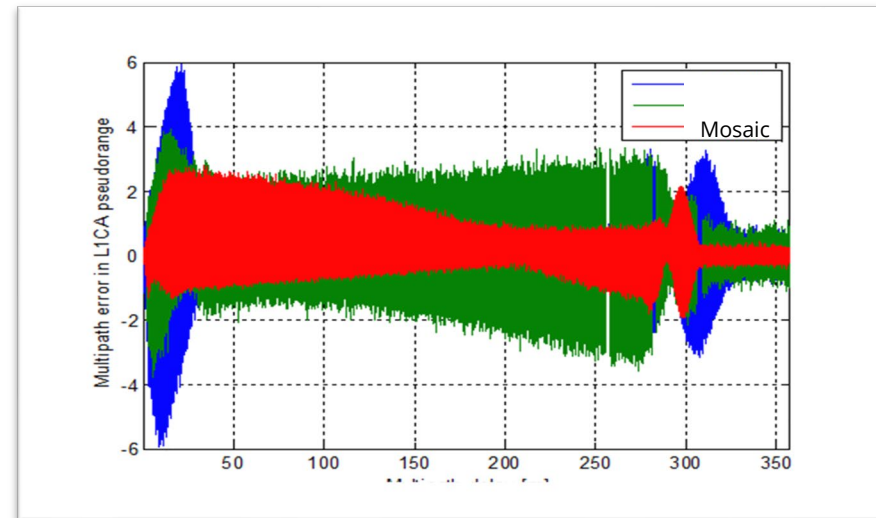
Multipath is the dominant error source in GNSS applications. It causes **meter-level error** on the measured satellite distances on both pseudoranges and carrier phases. It significantly degrades the position and time accuracy.

APME+ uses **extra correlators** in each tracking channel to **estimate the multipath error** on **pseudorange and carrier phase** measurements. Well, unlike most other techniques which only do code multipath estimation, APME+ support both code and phase multipath estimation. The measurements are then corrected by subtracting the estimated error. While most other multipath mitigation techniques involve modifying the correlators in the tracking channels, APME+ leaves the **tracking channels unchanged**. The multipath errors are estimated independently from the tracking of the signal.

On the other hand, APME+ is by design **free of any bias**. APME+ estimates the multipath error in **real-time** without modifying the underlying tracking loop.

Key Features

- Better against short delay multipath
- Estimates multipath without changing tracking loops
- Estimates multipath per satellite
- Indicates amount of multipath error
- Allows phase multipath

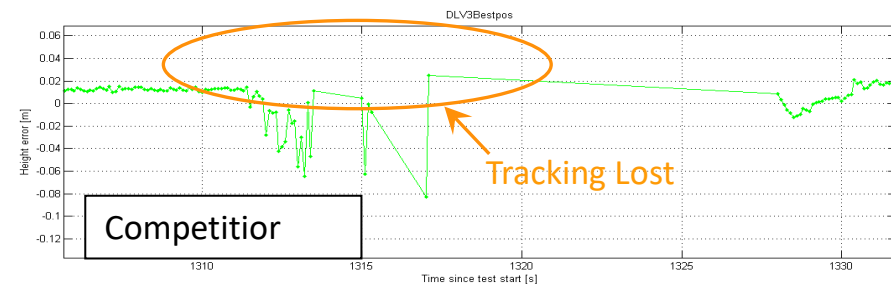
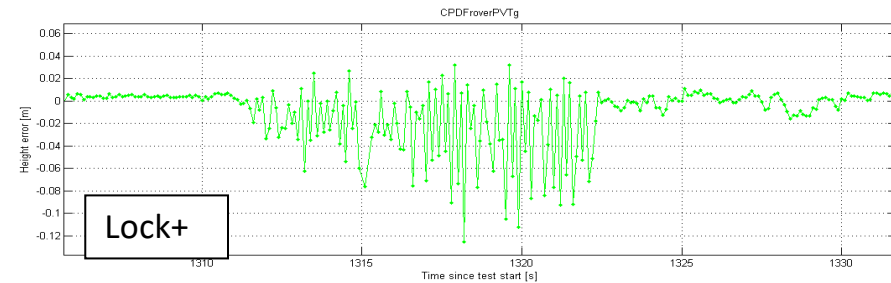


LOCK+

Superior Tracking Robustness

Machine vibration severely impacts tracking continuity which is harmful for RTK, PPP and heading positioning e.g. grade control

Special algorithms are implemented to maintain tracking under heavy vibrations.



AIM+ Advanced Interference Monitoring & Mitigation



Monitoring



AIM+ Interference Mitigation



Proven Performance

Septentrio's **AIM+** technology, the most advanced on-board interference mitigation technology on the market. It can **detect** and **suppress** the widest variety of interferers, from simple continuous **narrowband** signals to the most complex **wideband** and **chirp** jammers. The radiofrequency (RF) spectrum can be viewed in real-time in both time and frequency domains .

- **Monitor the RF spectrum**

You can monitor the RF spectrum in the Spectrum window of the GNSS menu.

- **Narrow-band interference**

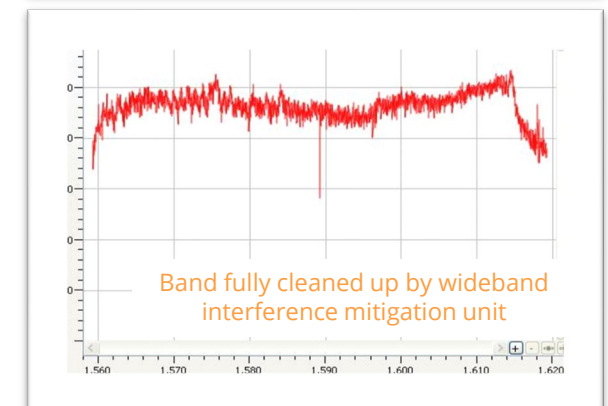
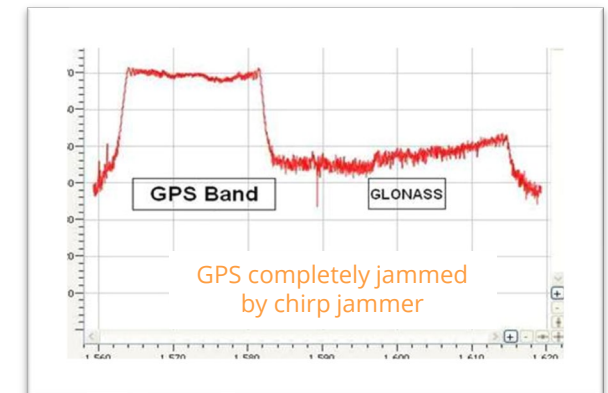
Narrow-band interference can be caused by electronic devices and affects only a small portion of the GNSS frequency spectrum. To mitigate the effects of narrow-band interference, 3 notch filters can be configured either in auto or manual mode. These notch filters effectively remove a narrow part of the RF spectrum around the interfering signal.

- **Wide-band and chirp interference**

The L2 band, being open for use by radio amateurs, is particularly vulnerable to this type of interference. The effects of wideband interference, both intentional and unintentional, can be mitigated by enabling the WBIM mitigation system. The WBI system also reduces, more effectively than traditionally used pulse-blanking methods, the effects of pulsed interferers.

- **Inmarsat and Iridium satellite interference**

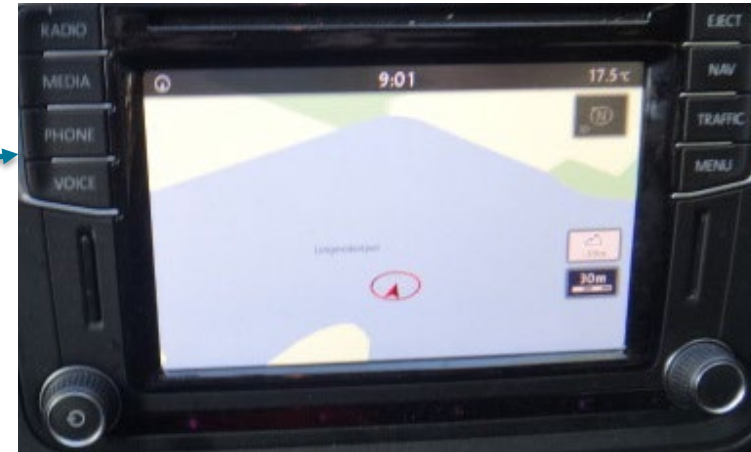
The mosaic can suppress the interference from high-powered Inmarsat and Iridium satellite communications signals.



Technology for Robustness – Spoofing

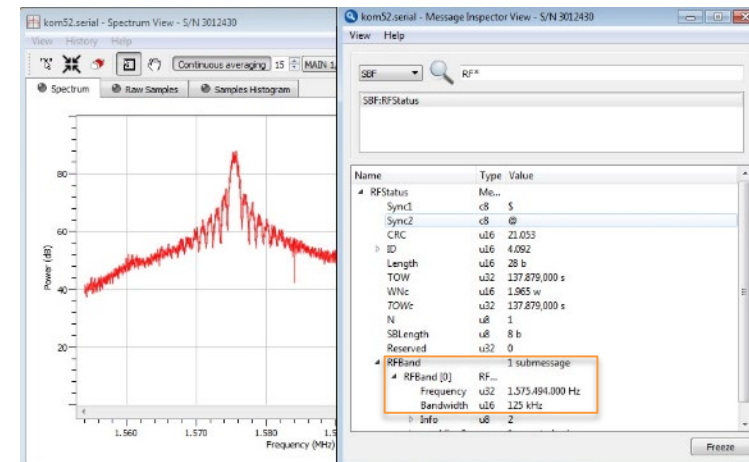
Spoofing is easy

Especially consumer/
L1



Septentrio :

- Several **built-in techniques** identify suspicious behavior
- Built-in spectrum analysis
- Signal characteristics & Timing
- And **compensate**
- Reject suspected signal
- Frequency diversity
- Continuously ongoing development





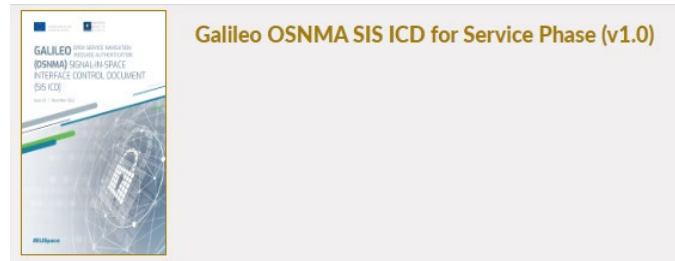
Galileo OSNMA

Open Service Navigation Message Authentication

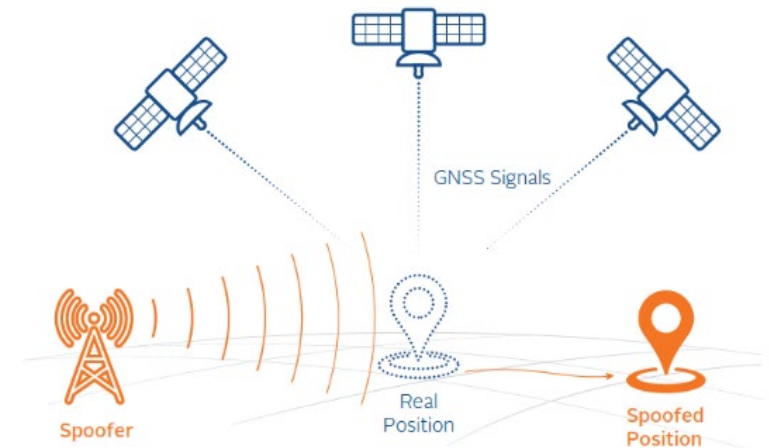
- **Spoof detection** by adding authentication (signature) of satellite nav message
- **Galileo** protected
- First ever signal-in-space authentication!
- Free of charge
- Backwards compatible

Timeline:

- 2023 Initial service



| | L5/E5 | L2 | L6/E6 | L1/E1 |
|---------|---------|----|-------|---------|
| GPS | L5 | L2 | | L1CA/C |
| Galileo | E5a E5b | | E6 | E1 |
| BeiDou | B2a B2b | | B3 | B1I B1C |
| QZSS | L5 | L2 | L6 | L1C/S |
| NavIC | L5 | | | L1C |
| SBAS | L5 | | | L1CA |
| GLONASS | | L2 | | L1 |



Septentrio GPS/GNSS receiver is the first to authenticate Galileo's newly developed end-to-end **OSNMA** encrypted signals.



High navigation rate, Low latency

- While tracking all satellites and all signals, positioning, raw data and heading can be output at 100Hz.
- Bulldozer blade control cannot maintain a constant height without low latency.

| | X module 10Hz | mosaic |
|-------------|------------------|--------|
| GPS+GLO+GAL | 75 ms | 6 ms |
| GPS+GLO | 50 ms | 5 ms |
| GPS+GLO+GAL | 75 ms | 5 ms |
| GPS+GLO | 50 ms | 4 ms |



PolaRx5 series

GNSS receivers for reference stations and scientific applications

PolaRx5 family

Multi-Frequency Multi-Constellation Reference Stations



PolaRx5 and PolaRx5e
CORS and scientific reference stations

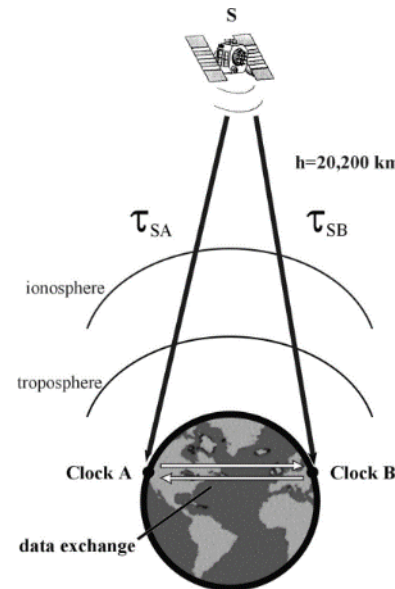
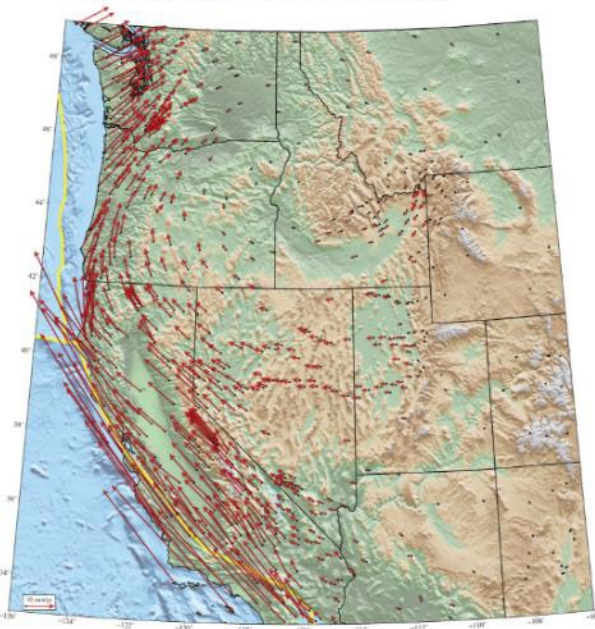


PolaRx5TR
Time transfer applications



PolaRx5S
Scintillation and ionosphere monitoring

Tectonic Motions of the Western United States



* CORS : Continuously Operating Reference Station

PolaRx5 – Differentiating Features

Best-in-class Measurement Quality

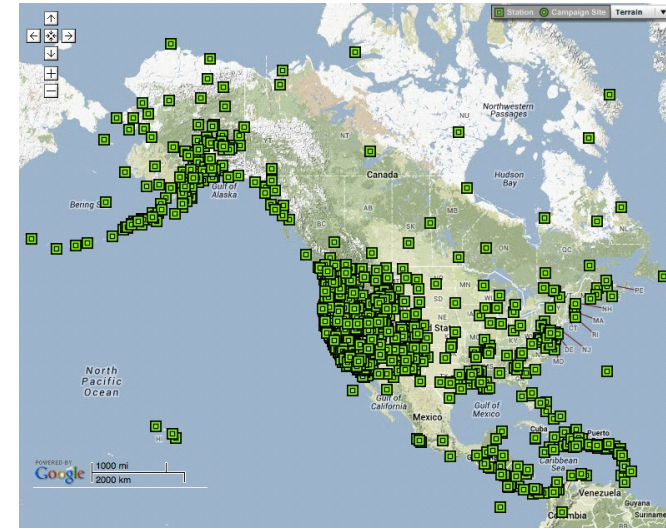
- High SNR, low cycle slips, high availability
 - Preferred UNAVCO GNSS Receiver
 - Evaluations 2015 <http://kb.unavco.org/kb/file.php?id=745>
- Provides GPS L1P and “real” raw data (no MP/smoothing)

APME+ Multipath estimation/mitigation

- Mitigates both code and carrier short-delay multipath
- Short-delay is most prevalent and damaging form of multipath
- Identifies amount of multipath present and can simultaneously provide unaltered data as well as with multipath eliminated
- Unaltered measurements, with no multipath estimated are provided also when APME is on (SBF MeasExtra)

The **UNAVCO** Endorsement

- UNAVCO is the largest single operator of GNSS reference stations: ~2,000 receivers (mostly NA)
- Septentrio selected as Preferred Vendor for GNSS Reference Stations since 2015 following 15 week RFP and technical evaluation period
- Key findings:
 - Best performance, esp. in multi-constellation testing
 - Scalable power consumption significantly lower than the competition
 - “Miles ahead” on interference mitigation
 - Superior technical support



<https://www.unavco.org/>

IGS Network

<http://igs.org/network>

1/3 of IGS GNSS network are PolaRx receivers.

Old PolaRx2/3 still active, demonstrating quality and durability of Septentrio receivers

IGS INTERNATIONAL GNSS SERVICE

Search

Filtered 176 from 516 stations



Station Overview ↑

Station Table ↓

| Site Name | Country/Region | Receiver | Antenna - Radome | Station |
|-----------|----------------|----------------|---------------------|---------|
| ABMF00GLP | Guadeloupe | SEPT POLARX5 | TRM57971.00 - NONE | GF |
| ABPO00MDG | Madagascar | SEPT POLARX5 | ASH701945G_M - SCIT | GF |
| AC2300USA | United States | SEPT POLARX5 | TRM59800.99 - SCIT | GF |
| AC2400USA | United States | SEPT POLARX5 | TRM159800.00 - SCIT | GF |
| ACSO00USA | United States | SEPT POLARX5 | TRM59800.80 - SCIT | GF |
| AGGO00ARG | Argentina | SEPT POLARX5TR | LEIAR25.R4 - LEIT | GF |
| ALBH00CAN | Canada | SEPT POLARX5 | TRM59800.00 - SCIS | GF |
| ALGO00CAN | Canada | SEPT POLARX5 | AOAD/M_T - NONE | GF |
| ALIC00AUS | Australia | SEPT POLARX5 | LEIAR25.R3 - NONE | GF |
| ALRT00CAN | Canada | SEPT POLARX5 | ASH701945D_M - NONE | GF |
| AMC400USA | United States | SEPT POLARX5TR | TPSCR.G5C - NONE | GF |

Show 25 stations



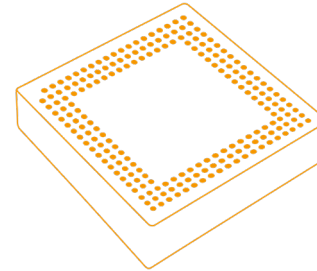
1 2 3 ... 8

Play Rotation ▶

516 Stations as of Aug. 29, 2023

Legend ⓘ

mosaic series



GNSS modules for large scale hi-accuracy applications

Small size with a wide array of HW / SW Interfaces

mosaic has a wide array of hardware and software interfaces in a **compact size** 3 x 3 cm LGA form factor working in a **industry temperature** environment. The USB device could be truned to 1 virtual ETH and 2 UARTs according to customer's OS. Together with 4 physical UARTs, 1 physical Ethernet, every interface could be used for SBF, NMEA, RINEX, RTCM, CMR input / output. If you use Ethernet interface, you could also use internal **UDP, TCP** Server/Client, **full-feature-ntp** Caster / Server / Client. SDIO interface is very useful for **data logging** to a max. 32G TF card independent of your applications.



Package

Type : SMT solderable LGA

Size : 31 x 31 x 4 mm

Weight : 6.8 g

Protocols

Septentrio Binary Format (SBF)

NMEA 0183, v2.3, v3.03, V4.0

RINEX v2.x, v3.x

RTCM v2.x, v3.x (MSM included)

CMR v2.0 (out/in), CMR+ (input only)

Environmental

Operational : -40 to +85 ° C

Storage : -55 to +85 ° C

Interfaces

4 UART (LVTTL, up to 4 Mbps)

Ethernet (RMII/MDIO), 10/100 Mbps

USB device (2.0, HS)

SDIO (mass storage)

2 GPIO user programmable

2 Event markers

1 Configurable PPS out



Maximize Uptime



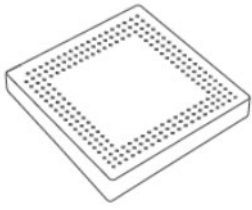
Feature Rich



Easy-to-integrate



Lightweight



mosaic

GNSS modules

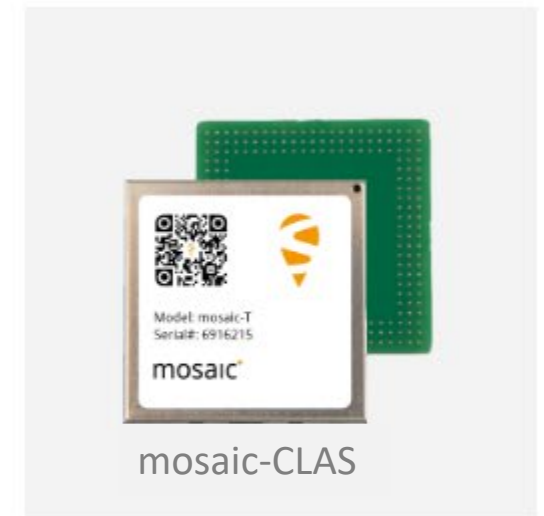
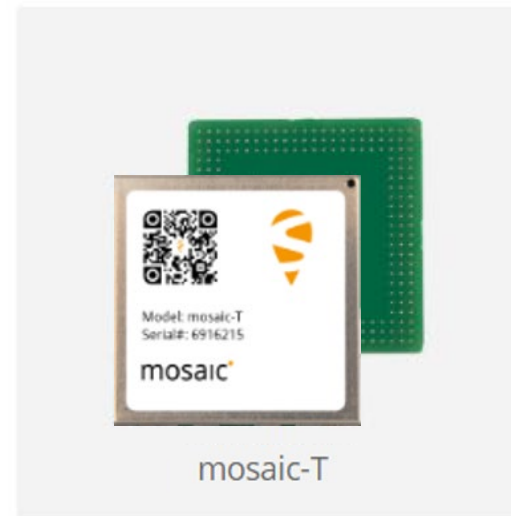
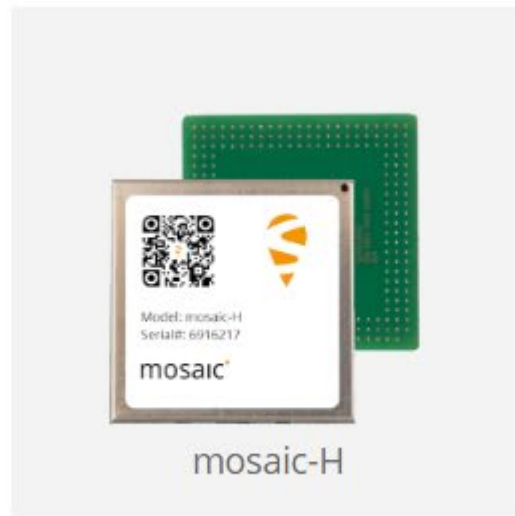
mosaic-CLAS the last from mosaic expansion

GNSS Performance

Dual Antenna Heading

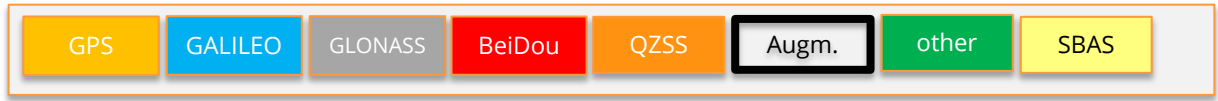
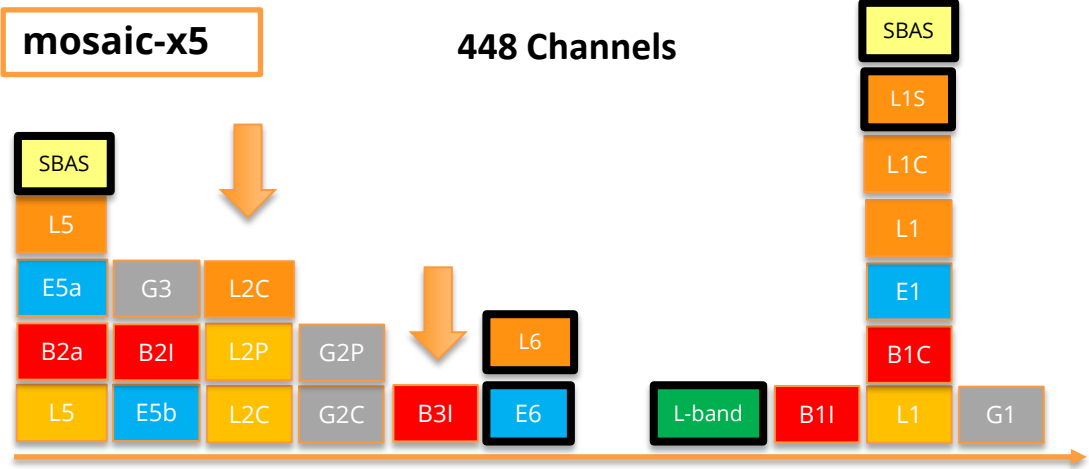
Timing

CLAS



mosaic-CLAS, only in Japan

Available Signals > competition

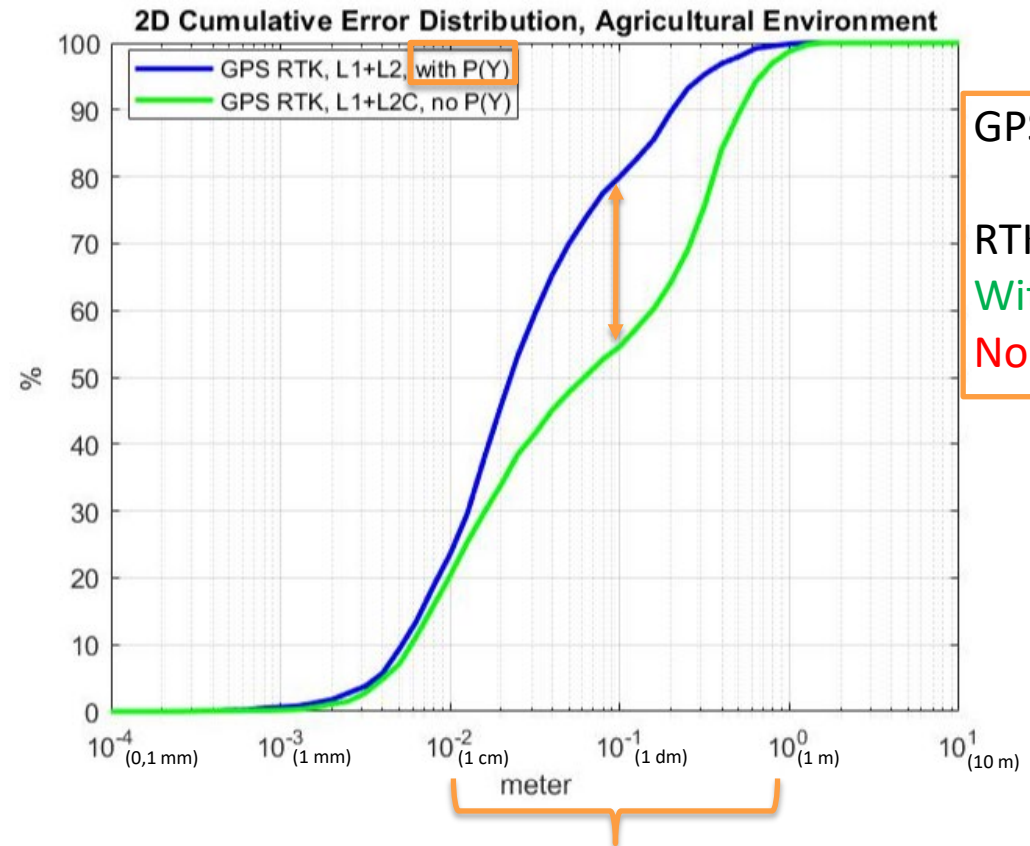


| | mosaic-x5 | Competitor A |
|----------|-----------|--------------|
| Channels | 448 | 184 |
| L2P | ○ | × |
| E5a | ○ | × |
| B3I | ○ | × |

RTK Availability with(out) P(Y) tracking



Test performed in an orchard in Torino, Italy on which the processing is based.



GPS L2P(Y) Code

RTK Fix :

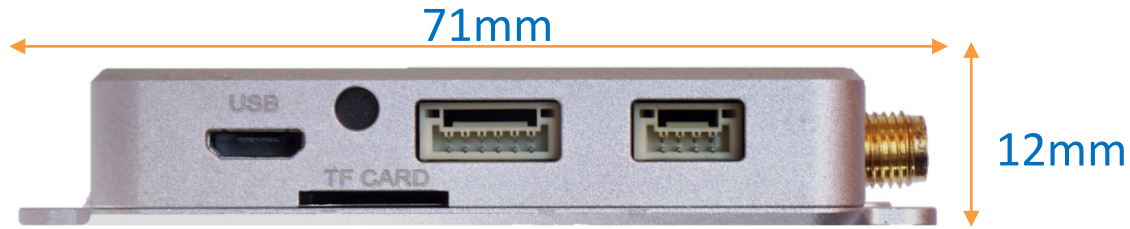
With L2P : 80%

No L2P : 56%

P-Code greatly increases the chances of having RTK for accuracies from 1cm-1m (most applications)

(Whether or not L2P (Y) Code reception is supported has a large effect on the RTK Fix rate.)

mosaic-go Evaluation Kit Product description



58 gramms

mosaic-go : 3 variants

1. mosaic-go is based on **mosaic-X5** one antenna connector
2. mosaic-go heading is based on **mosaic-H** Dual antenna connector
3. mosaic-go CLAS is based on **mosaic-CLAS** one antenna connector



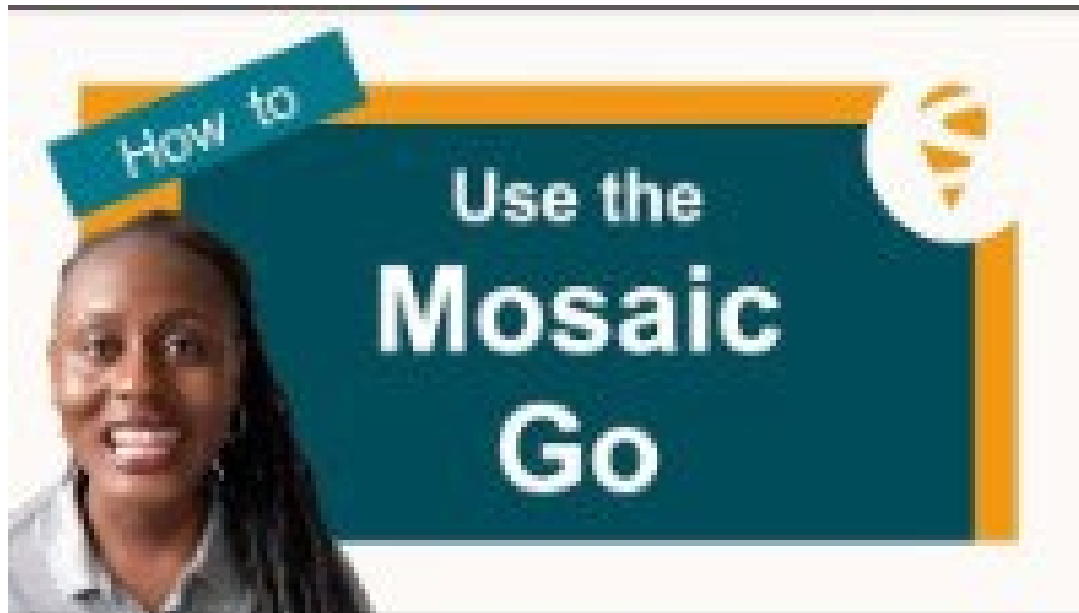
Documentations

Mosaic-go DataSheet are available from Septentrio web site:

Mosaic Hardware Hardware manual (Ver 1.8) includes :

- Complete description of mosaic-go (both for standard version and heading version)

How to Video and mosaic-go introduction is available on Septentrio support site



<https://www.youtube.com/watch?v=n1u5QZG4jls>

<https://shop.septentrio.com/en/shop/mosaic-go-gnss-module-receiver-evaluation-kit>

7 Evaluation Kit: mosaic-go



The mosaic-go Evaluation Kit is composed of the mosaic module soldered on an interface board inside a metallic housing.

Mosaic-go part number:

Single-antenna version, incorporating mosaic-X5: **410386** (including accessories).
Dual-antenna version, incorporating mosaic-H: **410397** (including accessories).

Dimensions: 71 x 59 x 12 mm ± 1 mm

Weight: 58 g ± 1 g

7.1 Interfaces

7.1.1 USB

This micro-B connector is used to access the mosaic-go over USB.

It can also be used to power the mosaic-go. See also section 7.4.

7.1.2 RSV USB

This connector is reserved and should not be used.

7.1.3 RF_IN1 and RF_IN2

These are the main and auxiliary antenna connectors, connected to the ANT_1 and ANT_2 pins of the internal mosaic. See section 3.2 for details.



Septentrio WEB Shop <https://shop.septentrio.com/en/shop>

PRODUCTS

Results 1 - 6 of 6



745,00 €

mosaic-go CLAS GNSS module receiver evaluation kit

Highly accurate GPS / GNSS receiver module, designed for the Japanese market

Complete multi-frequency, multi-constellation GNSS module receiver evaluation kit: GPS, GLONASS, Galileo, BeiDou, QZSS, NAVIC, Dedicated for the Japanese market

[More info >](#)



645,00 €

mosaic-go GNSS module receiver evaluation kit

Highly accurate GPS / GNSS receiver module

Complete multi-frequency, multi-constellation GPS module receiver evaluation kit: GPS, GLONASS, Galileo, BeiDou, QZSS, NAVIC

[More info >](#)



745,00 €

mosaic-go heading GNSS module evaluation kit

Highly accurate GPS / GNSS receiver module

Complete multi-frequency, multi-constellation GNSS module receiver: GPS, GLONASS, Galileo, BeiDou, QZSS, NAVIC

[More info >](#)



1.495,00 €

mosaic-H GNSS heading module development kit with 2 GNSS antennae

Highly accurate GPS / GNSS receiver module

Highly accurate GNSS - GPS heading module receiver evaluation kit for sale. Tracks GPS, GLONASS, Galileo, BeiDou, QZSS.

[More info >](#)



1.195,00 €

mosaic-T GNSS timing module receiver development kit with GNSS antenna

GPS / GNSS Timing receiver module

Complete multi-frequency, multi-constellation GNSS module receiver: GPS, GLONASS, Galileo, BeiDou, QZSS, NAVIC

[More info >](#)



1.195,00 €

mosaic-X5 GNSS module receiver development kit with GNSS antenna

Highly accurate GPS / GNSS receiver module

Complete multi-frequency, multi-constellation GNSS module receiver: GPS, GLONASS, Galileo, BeiDou, QZSS, NAVIC

[More info >](#)

simpleRTK3B Pro

Up to 100Hz RTK and down to 6mm accuracy with the most affordable L1/L2/L5 board in the market. Powered by Septentrio Mosaic-X5.



RTK3B Boards

simpleRTK3B Pro

From USD \$661.25

Select options

simpleRTK3B Heading

Dual antenna L1/L2/E5b RTK rover made simple for Position+Attitude up to 50Hz. Powered by Septentrio Mosaic-H.



RTK3B Boards

simpleRTK3B Heading

From USD \$862.50

Select options

simpleRTK3B mPCIe

The Septentrio Mosaic for embedded computers. In standard Mini PCI Express form factor.



RTK3B Boards

simpleRTK3B mPCIe

From USD \$688.85

Select options

simpleRTK3B Micro

The Septentrio Mosaic for small PCB integrators. In a reusable through hole form factor so you don't risk it if something goes wrong with your PCB design or assembly.



RTK3B Boards

simpleRTK3B Micro

From USD \$688.85

Select options

mosaicHAT

An open source GNSS HAT for Raspberry Pi

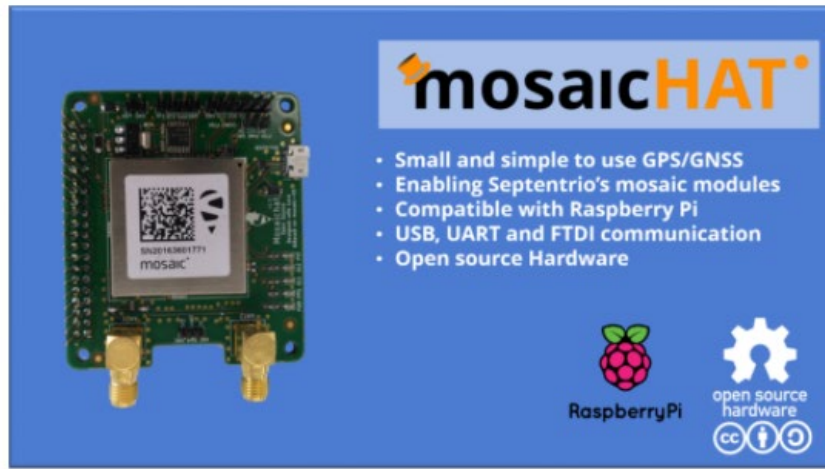
mosaicHAT: A GNSS HAT for Raspberry Pi

Author: (Jamal Sa'd) jamalhazem127@gmail.com

Maintainer: (Septentrio gnss github user) githubuser@septentrio.com

External website: <https://github.com/septentrio-gnss/mosaicHAT>

License: Creative Commons Attribution Share-Alike License. and Open Source HW



Click to watch this video introducing mosaicHAT



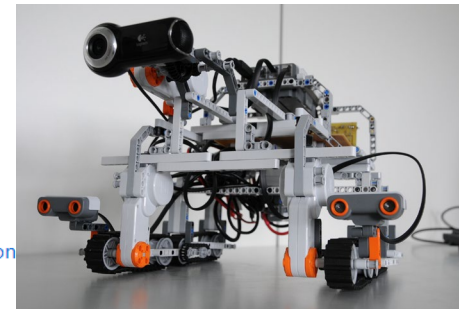
All documented

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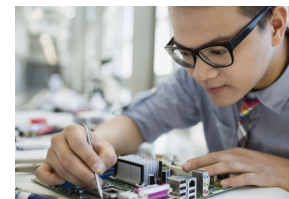
- Introduction to mosaicHAT
 - What is mosaicHAT?
 - A HAT for Raspberry Pi?
 - What is the mosaic module?
 - Who is Septentrio?
 - Is the project Open Source?
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 - Connecting to Raspberry Pi
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 - Events and PPSO
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 - Clock Frequency Reference
- Further improvements

Intro for new people
What is mosaic, Septentrio,
etc,.

User documentation



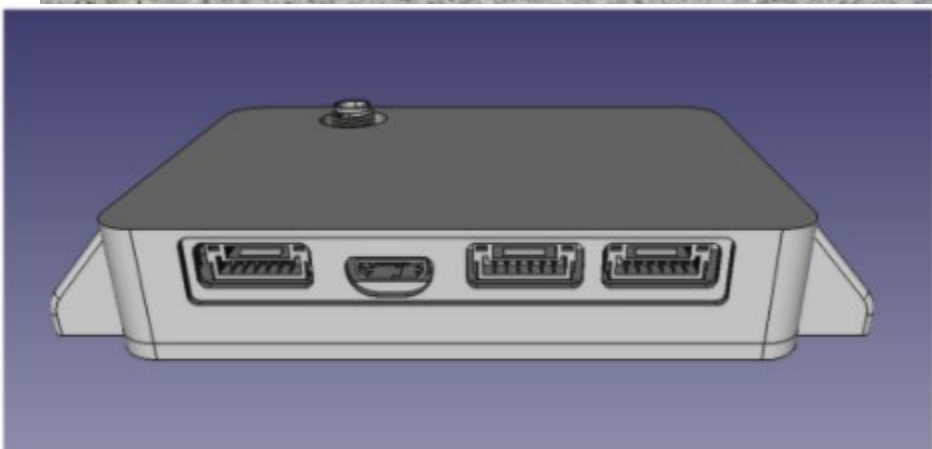
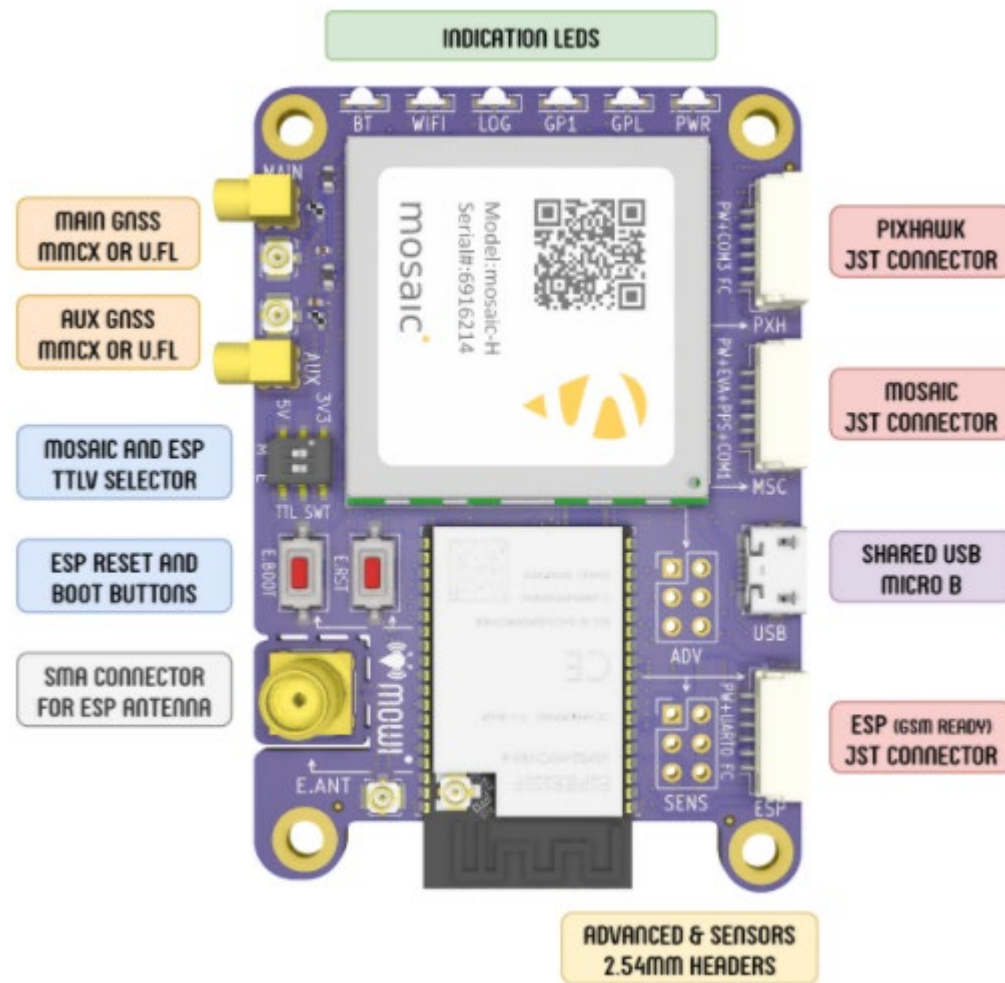
Designers



<https://www.youtube.com/watch?v=5LeuElfyvlg>

mowi

<https://github.com/septentrio-gnss/mowi>



Pains when starting projects



Engineer wants **compatibility**
Engineer searches for **open source**
Engineer wants **ease** of test
Engineer wants to **source easily**



What we are doing to expand ecosystems?

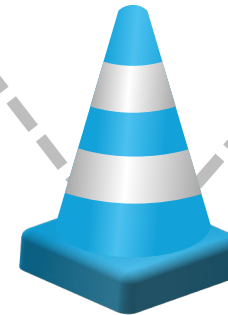
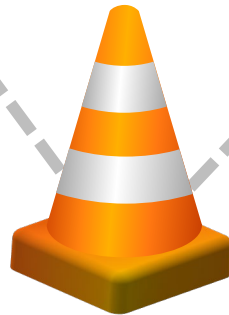
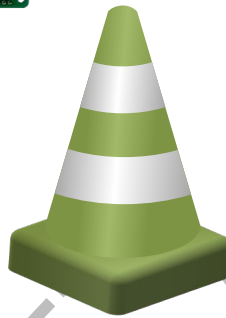
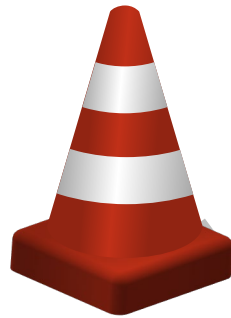
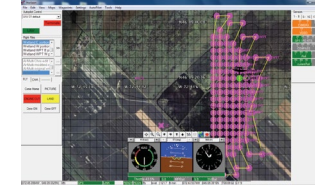
OPEN SOURCE HW

- mosaicHAT
- Mowi



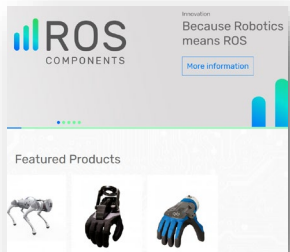
OPEN SOURCE SW (DRIVERS)

- PX4
- Ardupilot
- ROS



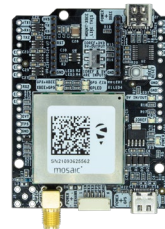
CHANNELS

- Digikey
- ROS Components
- Spectroworks
-



MOSAIC HW ENABLERS (EVAL SYS)

- ArduSimple
- Sparkfun
- GNSS Store (Elthes)
- Mikroelectronica



CO-MARKETING

- Micropilot
- Xsens
- ...





NMEA Navsat driver This package provides a ROS interface for GPS devices that output compatible NMEA sentences. The driver is generic enough to work with several GNSS receiver types including Septentrio GNSS receivers. Please also take a look at the ROSaic project which offers full support for SBF.

Solution: ROS Driver

Product link: [All Septentrio Products](#)

Tags: #opensource, #ROS, #robotics #autonomous #rosdriver #nmea

[Visit partner website](#)

The **Pixhawk** flight controller board is a flexible autopilot intended primarily for manufacturers of UAV commercial systems. Its HW can be used with Septentrio receivers specially when in combination with Ardupilot SW.

Solution: Pixhawk

Product link: [mosaic-X5](#), [mosaic-H](#), [AsteRx-m3](#), [AsteRx-i3](#)

Tags: #opensource, #autopilots, #uavs #flightcontroller

[Visit partner website](#)

PX4 autopilot is one of the largest commercially adopted open-source navigation control stacks, enabling an innovative community to build and maintain drone hardware and software in a scalable way. Septentrio [AsteRx-m3](#) and [mosaic](#) receivers are compatible with **PX4** autopilots, with both single antenna and dual antenna configurations, which offer either heading and pitch or heading and roll angles on top of accurate GNSS positioning. With this open-source copy of the official PX4 repository you can get started with Septentrio receivers working seamlessly with PX4.

Solution: [PX4 Driver](#) on GitHub

Product link: [mosaic](#), [AsteRx-m3](#)

Tags: #opensource, #autopilots, #uavs #flightcontroller

[Visit partner website](#)



ROSaic is an open-source ROS driver for mosaic and other Septentrio GNSS receivers. The ROS driver is a ROS node that makes the Septentrio GNSS hardware accessible from ROS (Robotics Operating System). Robot Operating System is robotics middleware. Although ROS is not an operating system, it provides services designed for a heterogeneous computer cluster such as hardware abstraction, low-level device control, implementation of commonly used functionality, message-passing between processes, and package management. [This page contains links to many resources to assist integration of GNSS in ROS, with the help of ROSaic.](#)

Solution: ROS driver

Product link: [mosaic-X5](#), [mosaic-H](#), [AsteRx-m3](#), [AsteRx-i3](#), [AsteRx-SB3](#), [AsteRx-SBI3](#), [AsteRx-U3](#)

Tags: #opensource, #ROS, #robotics #autonomous #ROSdriver

[Visit partner website](#)

Summary

- **High accuracy GNSS is a good place to be as a young engineer**
 - Use will only increase.
 - GNSS is the key enabling technology to automate outdoor tasks.
 - LEO PNT being developed to complement GNSS
- **Septentrio is a good choice**
 - Most accurate and reliable GNSS position and timing solutions in the most demanding industrial and scientific environments.
 - Web interfaces, tools and utilities, raw data, IMU/INS fusion.
 - Protection against interference.
 - Support for open-source eco-systems

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Thank you - Questions





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